



Mapping Vector Codes to Stream Processor (Imagine)

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Outline

- Motivation
- Problem Statement
- Simulation Results
- Conclusion

Motivation

- Large volume of vector code in existence
 - ◆ Arithmetic intensive
- Much existing research on vectorization
 - ◆ Vectorizing compilers, etc.
- Stream programming
 - ◆ Intermediate data
 - ◆ Producer-consumer locality
 - ◆ Shorter lifetime than in vector processor

Problem Statement

Efficient mapping of vector codes to stream processor

- ◆ Pseudo vector code
 - ◆ Not focusing on syntax
- ◆ Focus on specific hardware
 - ◆ Imagine architecture
 - ◆ Imagine programming model
 - ◆ Stream C & kernel C
 - No performance evaluation in Brook

Goals

- **Maximize resource utilization**
- **Minimize memory bandwidth requirements**
 - ◆ SRF \leftrightarrow LRF
 - ◆ SRF \leftrightarrow μ C
- **Minimize inter-cluster communications**
 - ◆ Specially for vector reduction operations
 - ◆ Inner-product, matrix \times vector, ...

Approach

- Implementation in KernelC & StreamC
 - ◆ Cycle accurate simulation
 - ◆ Various representative code snippets
 - ◆ Various record sizes
 - ◆ Various kernel granularity
 - ◆ Considering realistic settings
- Observations through simulation
 - ◆ Interpret results
 - ◆ Look for rules
 - ◆ Can be applied to mapping strategy

Partitioning

● Modulo Data

◆ Stream element size

$$C[15:0] = A[15:0] + B[15:0]$$

```
record vect {float v0, ..., vn;}
```

```
kernel VADD(istream<vect> A, istream<vect> B, ostream<vect> C)
```

● Modulo Operation

◆ Kernel granularity

$$C[15:0] = A[15:0] + B[15:0]$$

$$E[15:0] = C[15:0] \cdot D[15:0]$$

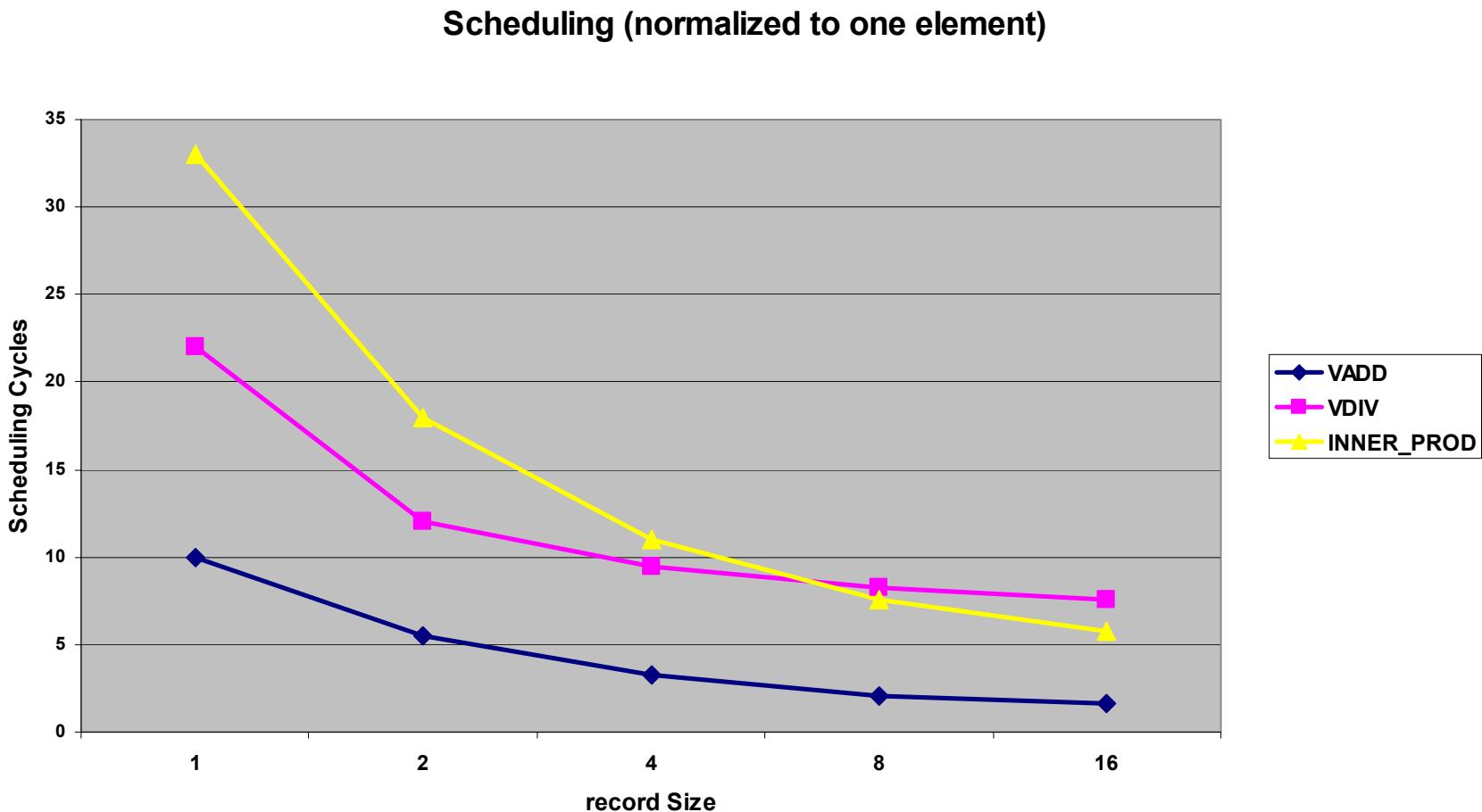
```
kernel VADD(A,B,C)
```

```
kernel VMUL(C,D,E)
```

```
kernel VADD_MUL(A,B,D,E)
```

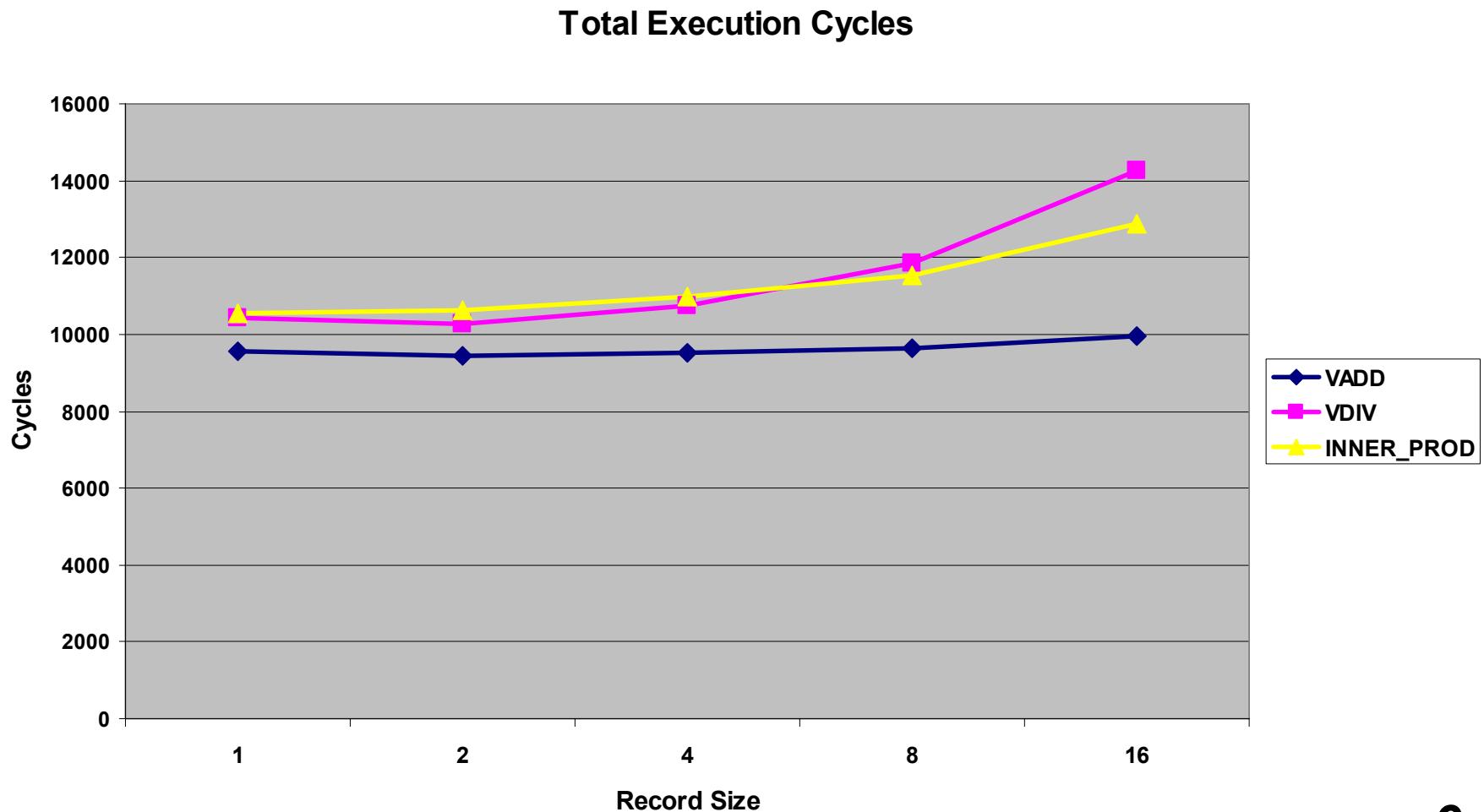
Effect of Record Size on Scheduling

- Better scheduling with larger record sizes
- Unrolling has the same effect of increasing record size



Total Execution Time

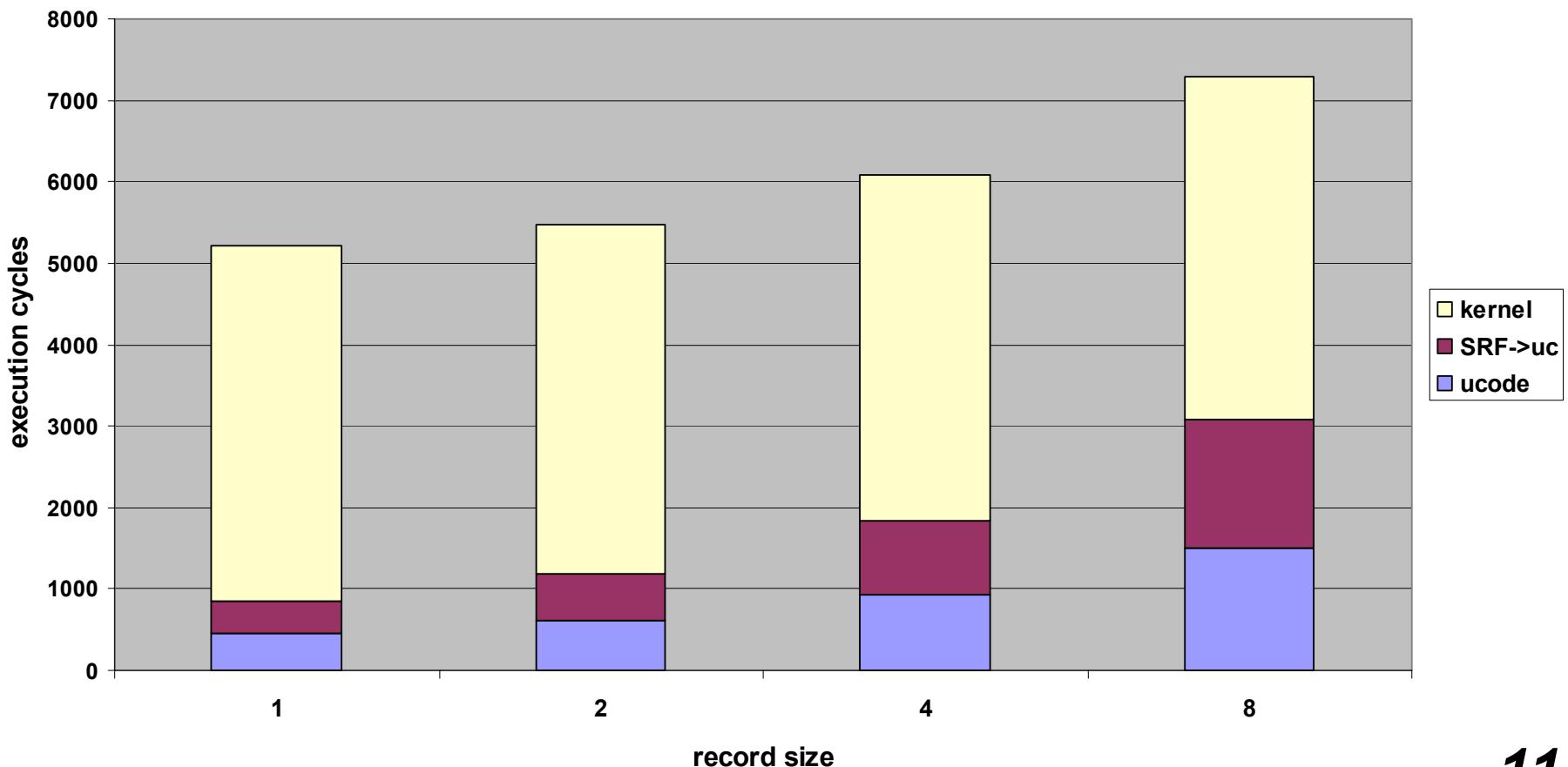
- Not as expected!!!



Why Worse?

Reason

Detailed cycle count

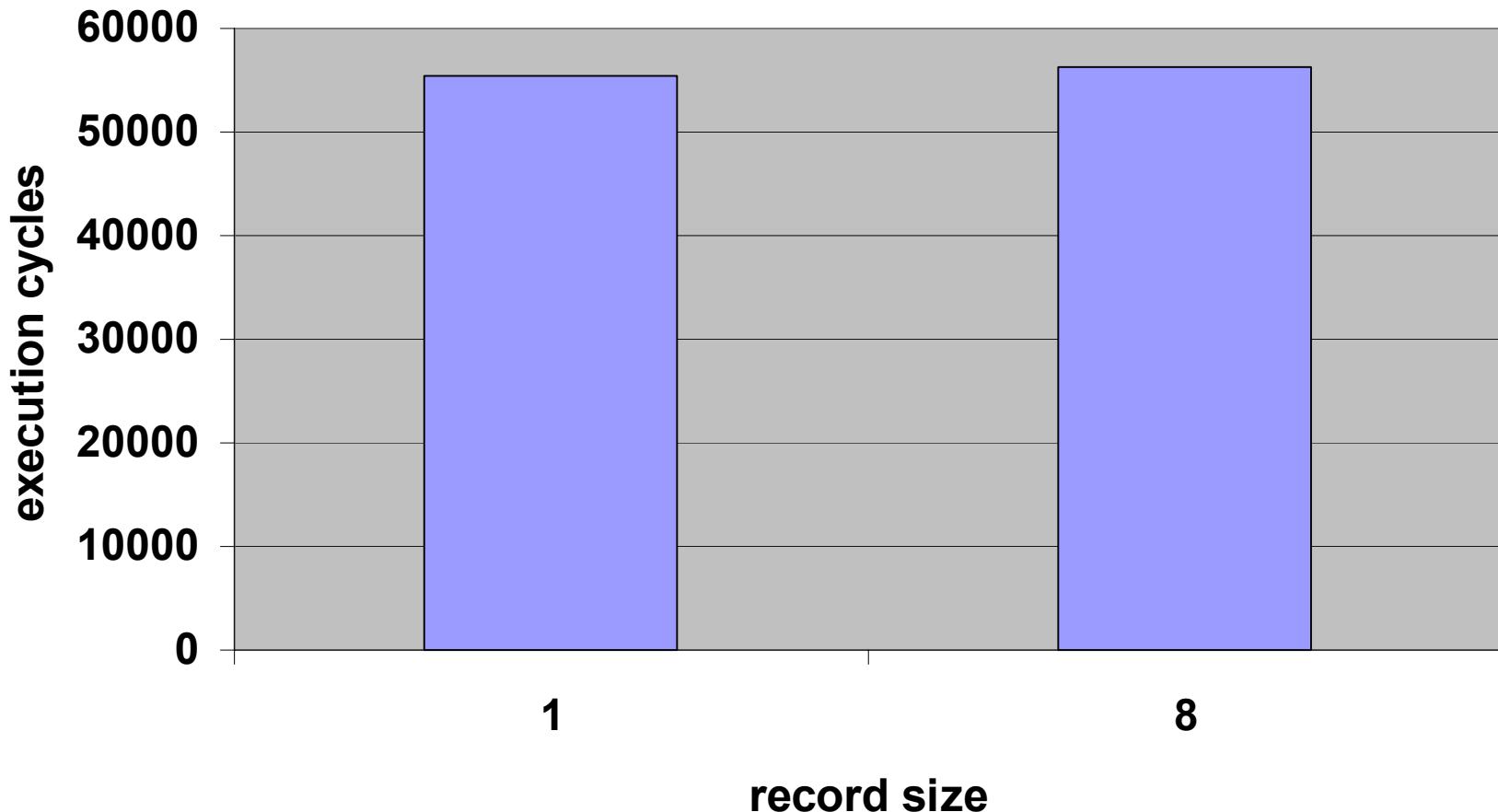


μ Code

- μ Code is first loaded to SRF
- Then loaded from SRF to μ Controller
- Record size $\uparrow \Rightarrow \mu$ Code size \uparrow
- μ Code cost can be *amortized*
 - ◆ reusing the same kernel
- Less of an issue for larger data sets

Amortized μ Code

10 ADD kernels

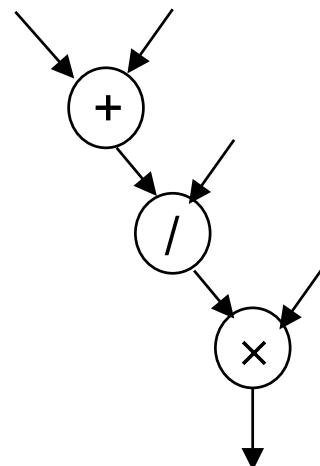


Kernel Granularity

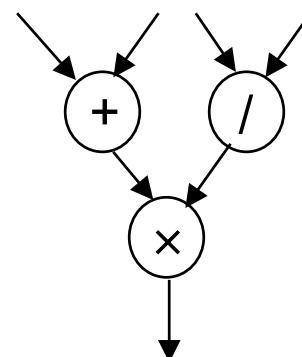
- Extreme cases:

- ◆ Each operation in a separate kernel
- ◆ All operations in one big kernel

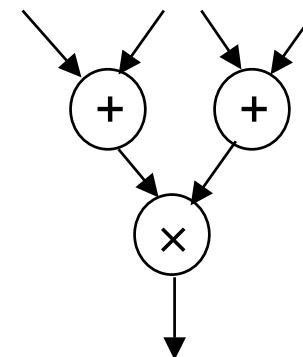
$$\begin{aligned}T1 &= V1 + V2 \\T1 &= T1 / V3 \\V_o &= T1 \times V4\end{aligned}$$



$$\begin{aligned}T1 &= V1 + V2 \\T2 &= V3 / V4 \\V_o &= T1 \times T2\end{aligned}$$



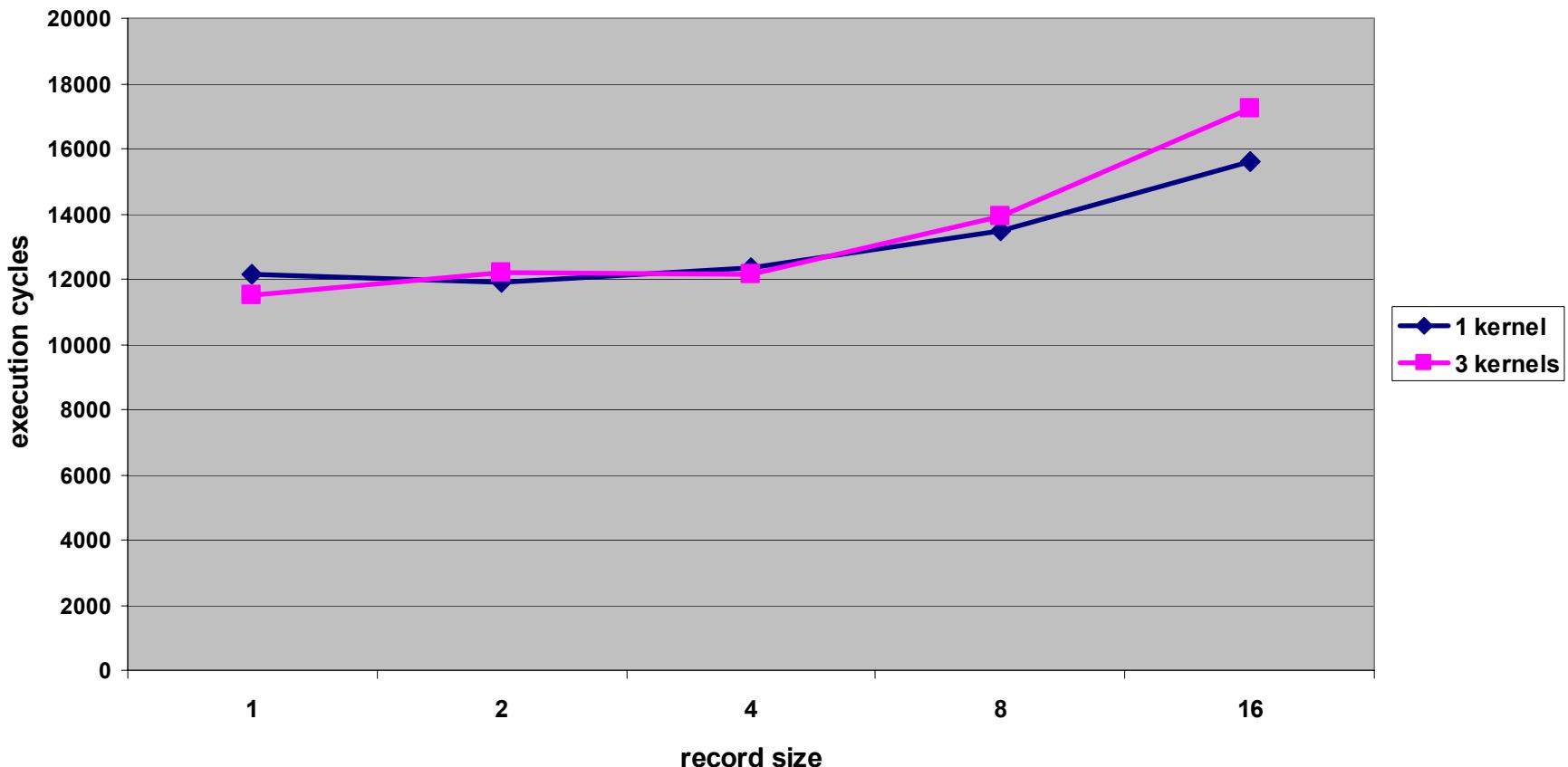
$$\begin{aligned}T1 &= V1 + V2 \\T2 &= V3 + V4 \\V_o &= T1 \times T2\end{aligned}$$



Serial Computations

- 256 data set
- No software pipelining in kernel scheduling

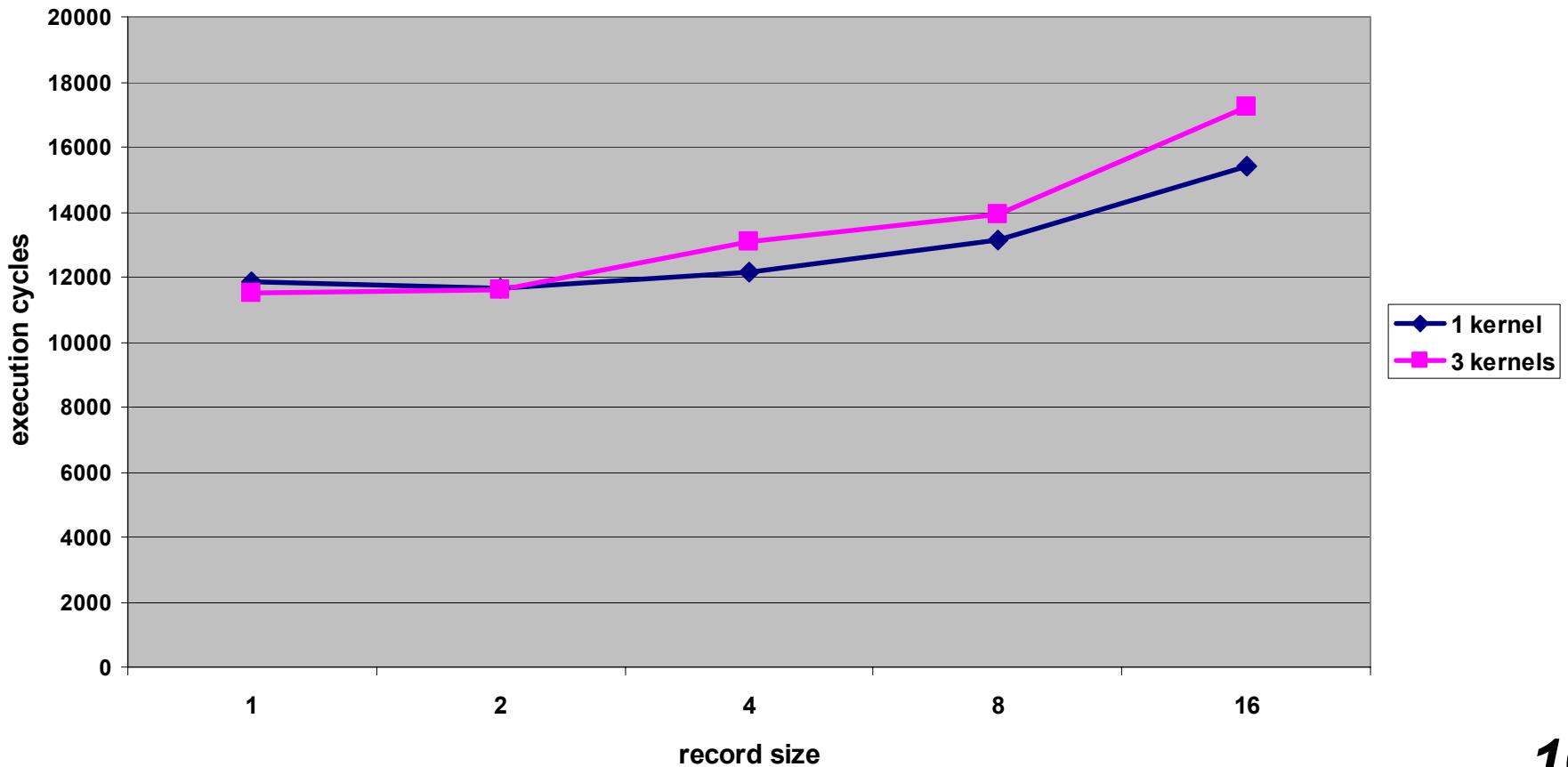
$$V_o = ((V1 + V2) / V3) \cdot V4$$



Non-serial Computations

- 256 data set
- No software pipelining in kernel scheduling

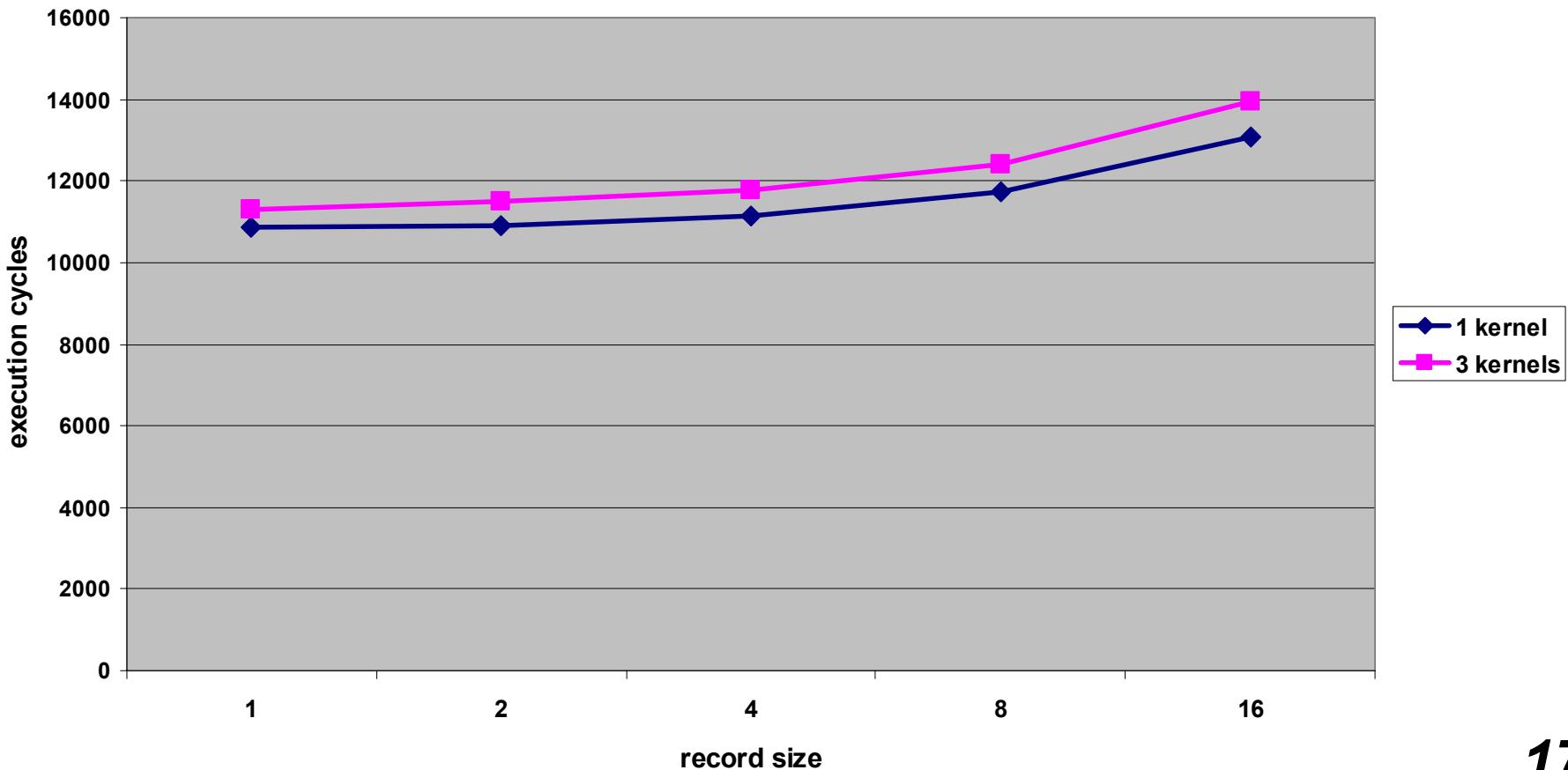
$$V_o = (V_1 + V_2) . (V_3 / V_4)$$



More Non-serial Computations

- 256 data set
- No software pipelining in kernel scheduling

$$V_o = (V1 + V2) . (V3 + V4)$$



Two cases

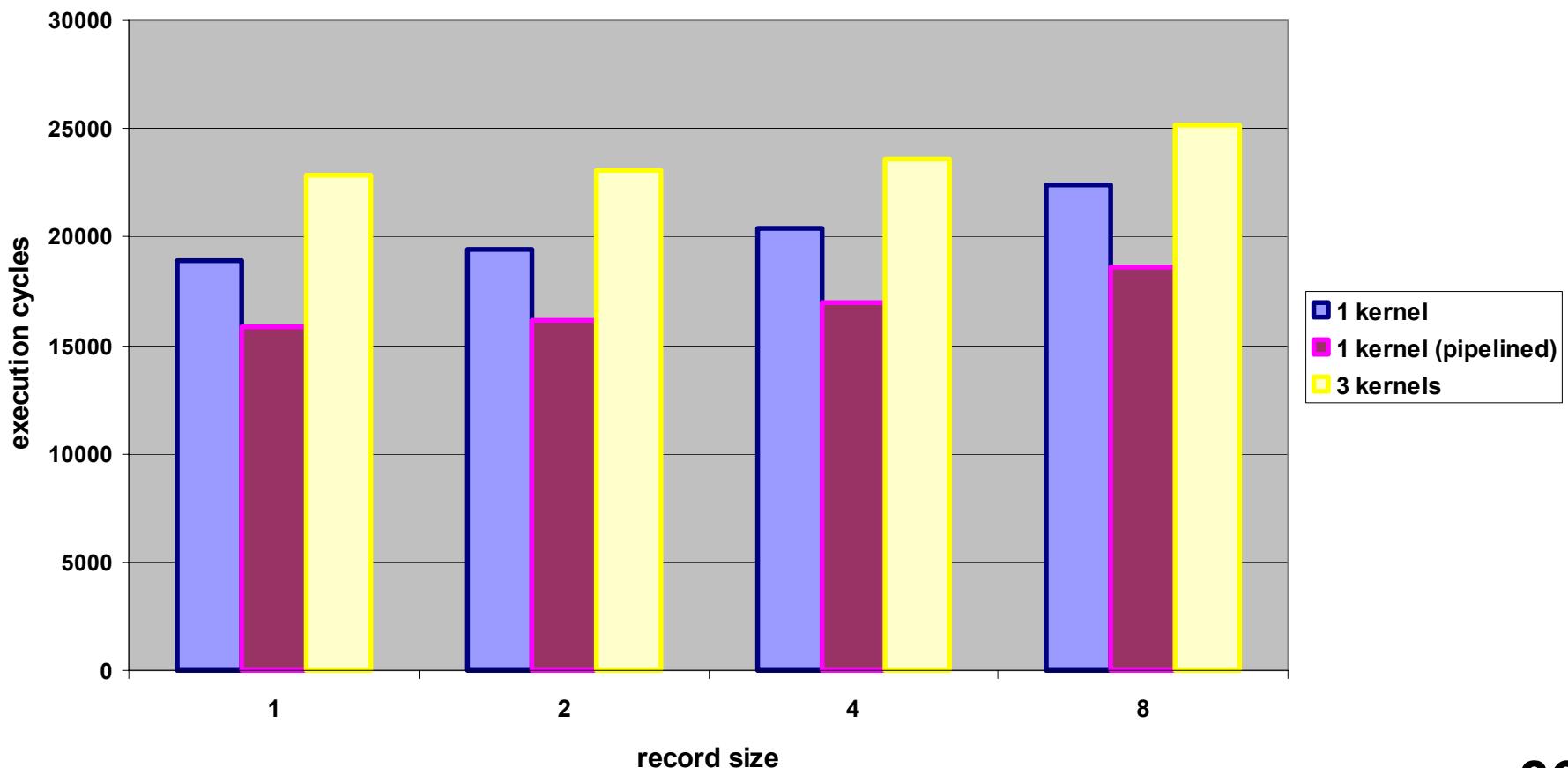
- For serial computation
 - ◆ Smaller kernels with smaller record sizes
 - ◆ Best performance
- For non-serial (parallel) computation
 - ◆ Bigger kernels always better
 - ◆ Better resource utilization

More Simulations

- Computational intensive operations
 - ◆ Heavy loops
 - ◆ Carry independent
 - ◆ Large Matrix by Vector manipulation
- Effect of software pipelining
 - ◆ Better resource utilization

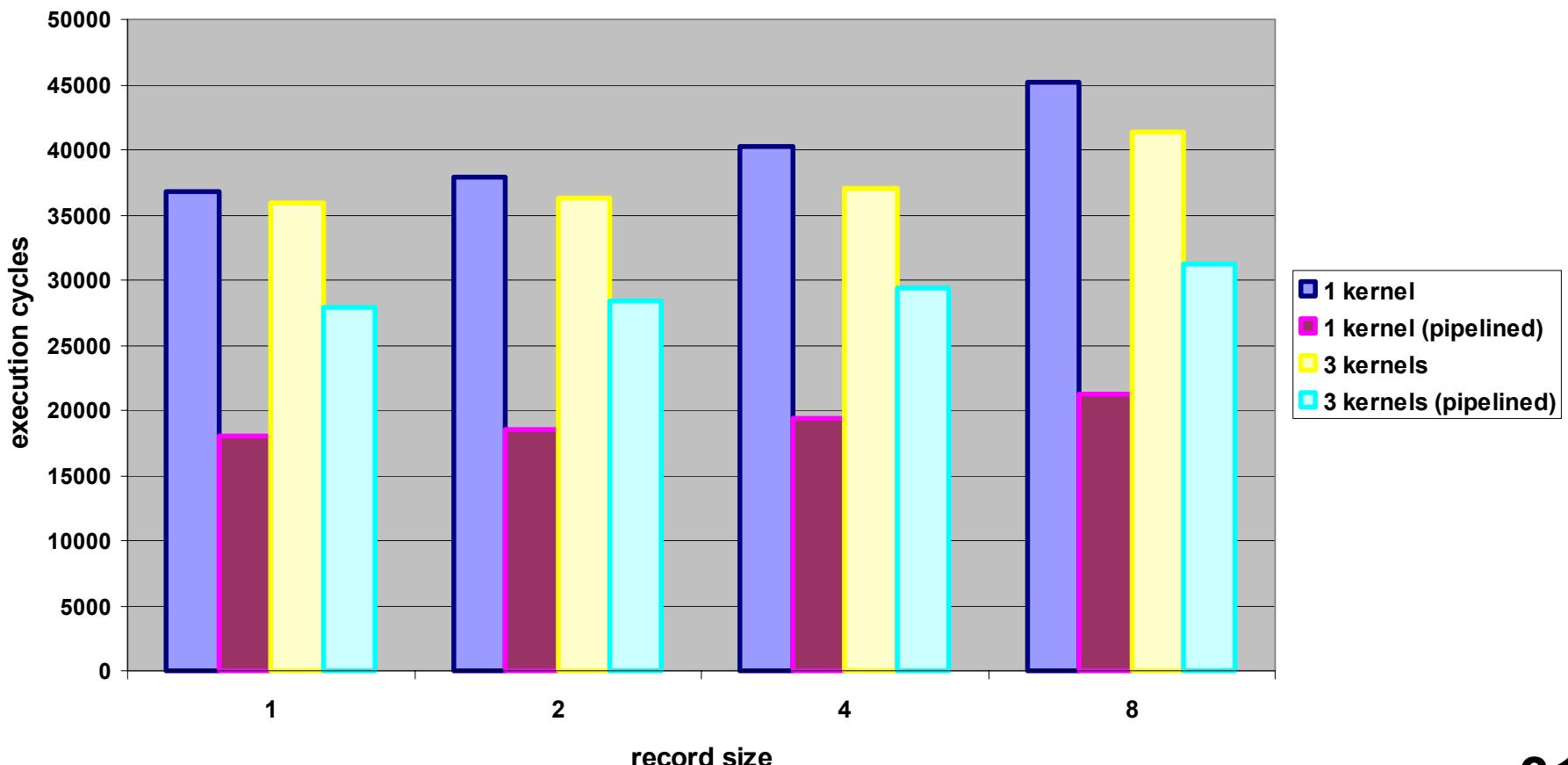
Non-Serial Computation

Loops of $(V1 + V2) . (V3 + V4)$



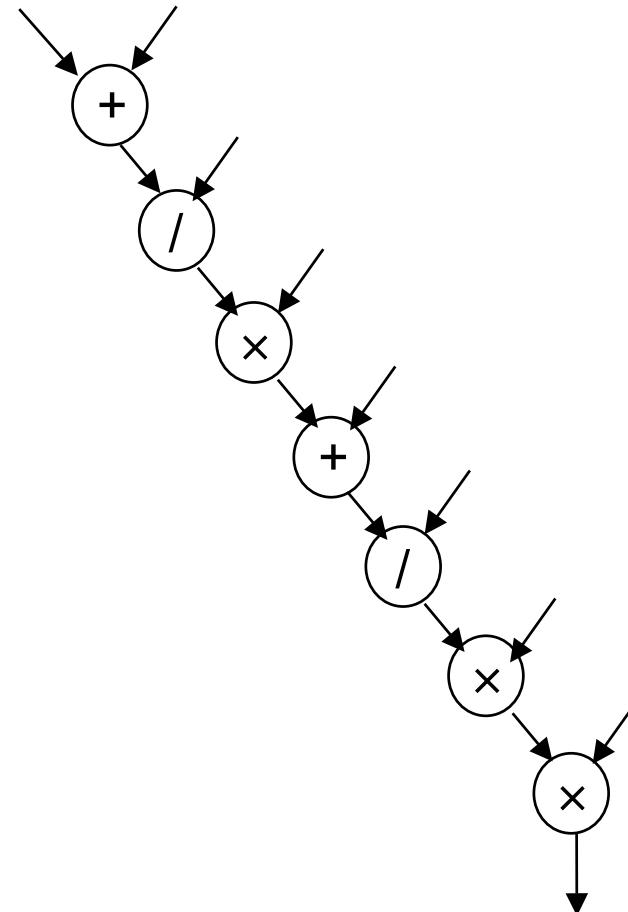
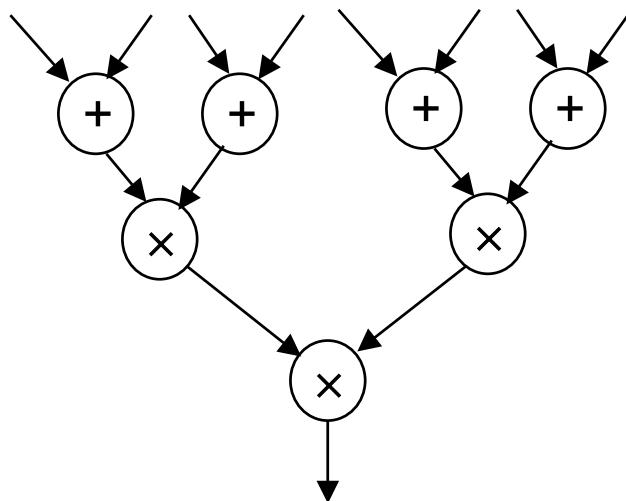
Serial Computation

Loops of $((V1 + V2) / V3) . V4$



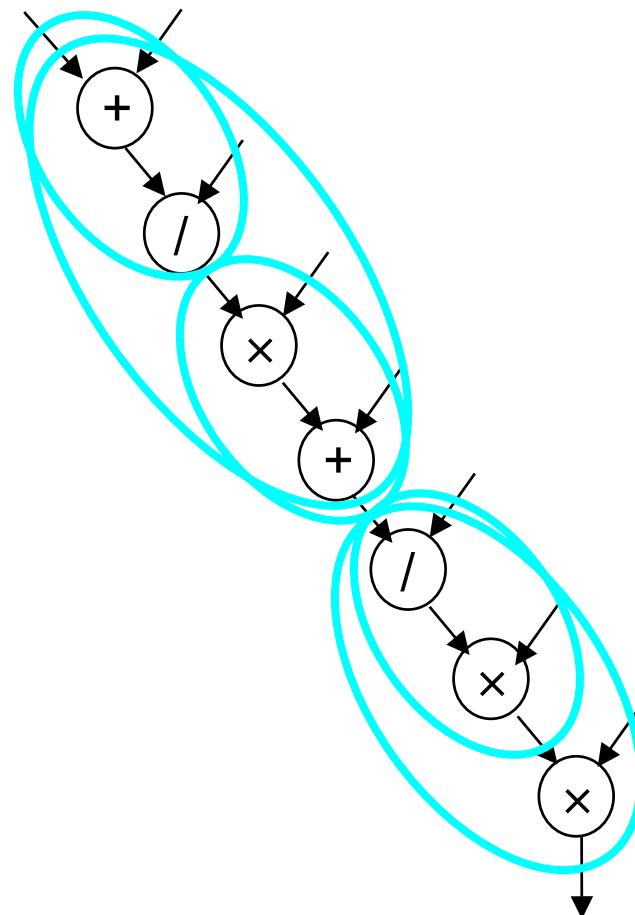
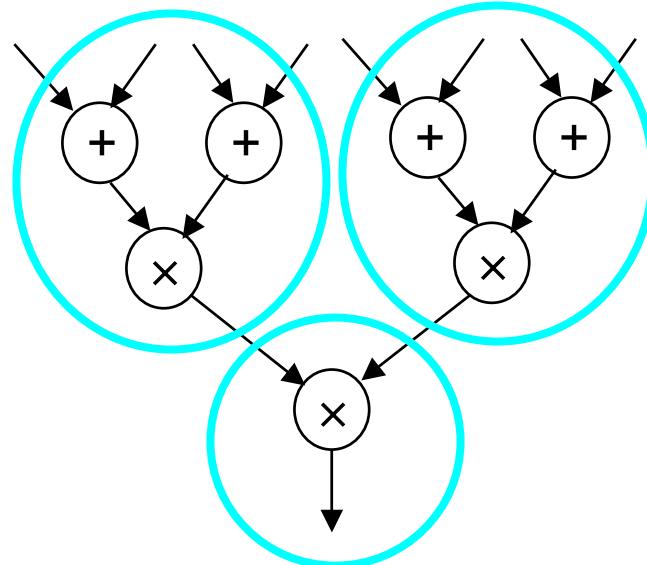
Larger Case

- Two Dataflows
 - ◆ Balanced tree
 - ◆ Fully dependent

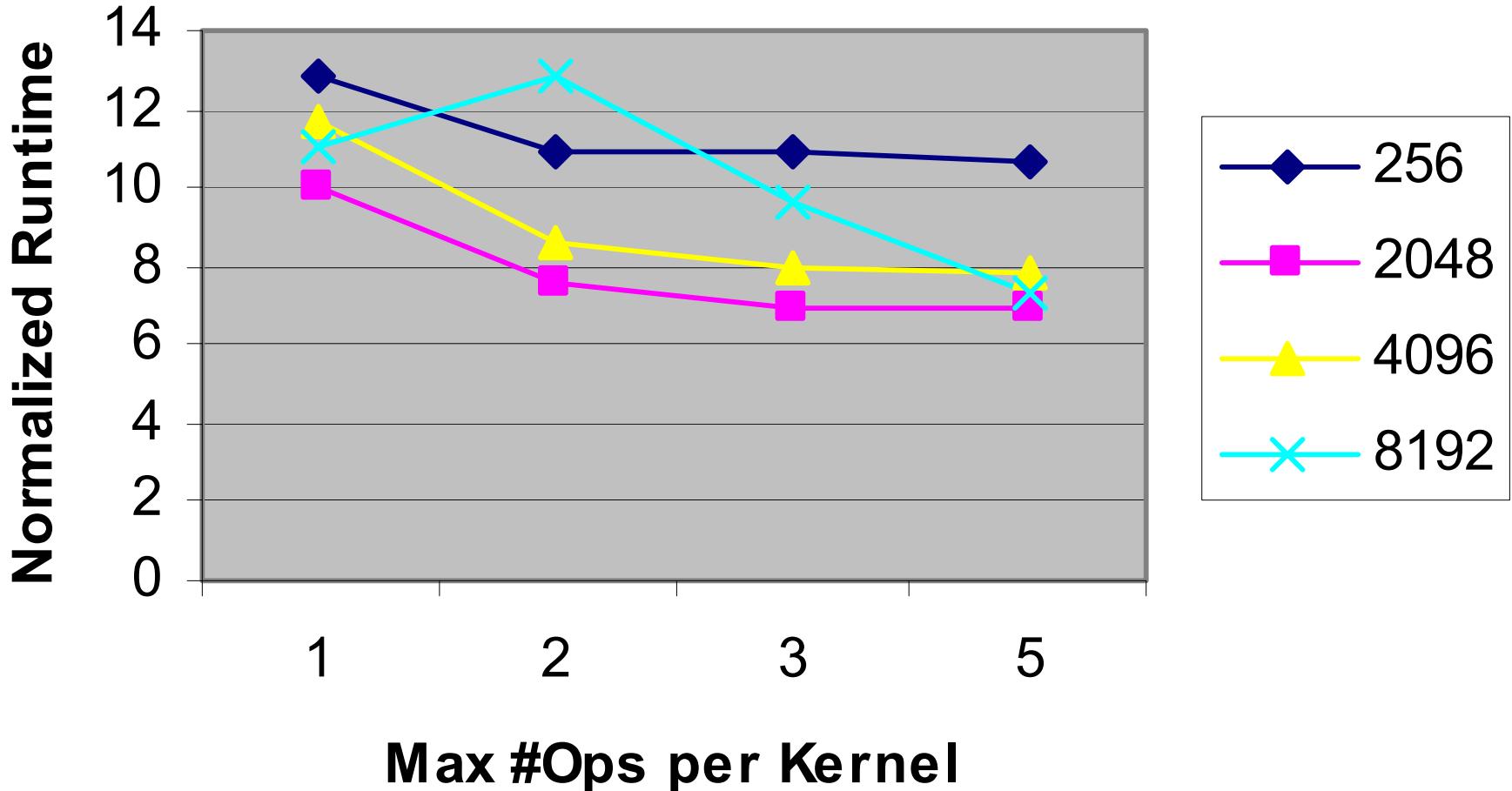


Kernel Fusion

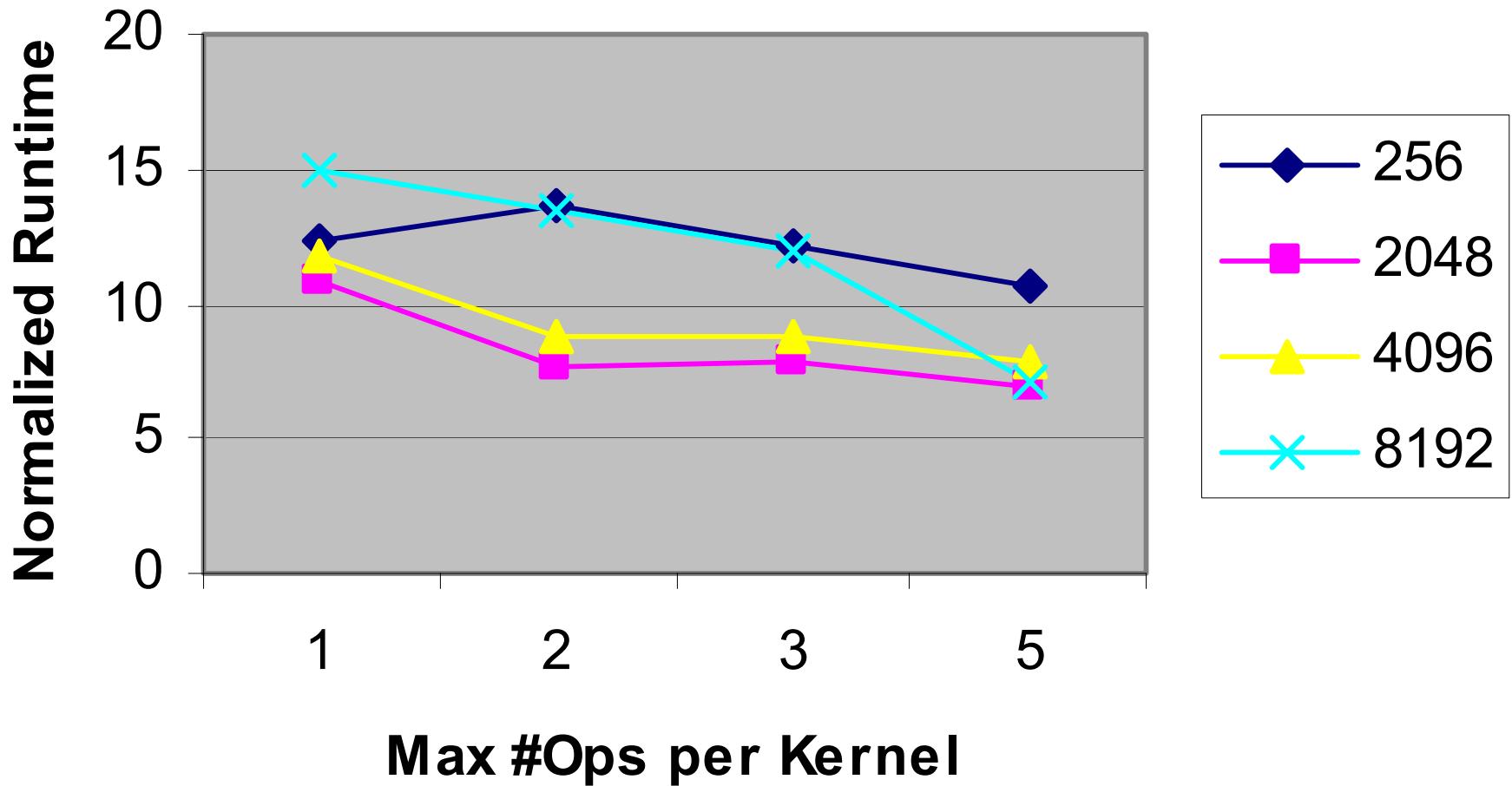
- Essentially kernel fusion
 - ◆ Merge 1-op kernels



Serial Chain



Parallel Chain



Kernel size

- Larger kernels are better for reasonable data size
 - ◆ More ops to schedule
 - ◆ Once there are enough ops, no more benefit
 - ◆ But, for data size comparable to SRF, large kernels still better
- Limits to kernel size
 - ◆ LRF size limit
 - ◆ Limit to number of streams per kernel

Conclusion

- Explored basic issues of mapping vector code to stream code
 - ◆ Mostly confirmed intuition
 - ◆ Found a few issues we did not consider
- Next logical step : set of criteria for kernel fusion
 - ◆ Need to satisfy many constraints
 - ◆ Best solution may be impractical to find
 - ◆ Set of heuristics would probably suffice